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TECHNICAL JOB SPECIFICATION

610/2

REVISION 0

DATE 29/06/2011

LNG PLANT

INSTRUMENTATION SYMBOLS AND IDENTIFICATION



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REVISIONS LOG

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REFERENCED DOCUMENTS

1. ISA S5.1 (1984)
[Instrumentation Symbols and Identification]

2. ISA S5.3(1983)

[Graphic Symbols for Distributed Control / Shared Display Instrumentation Logic and Computer Systems]

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1.0 **GENERAL**

Instruments shall be identified by a system of letters and numbers generally in accordance with the Instrument Society of America (ISA) Standards S5.1, and S5.3 last edition, extracts from which follow. Minor modifications have been made, in this specification.

Each instrument will be identified first by a system of letters used to classify it functionally. (See **Tables 1 and 2** for the system of letters). To establish a loop identity for the instrument, a number will be appended to the letters. This number will, in general, be common to other instruments of the loop of which this instrument is a part. A suffix is sometimes added to complete the loop identification.

Where **ISA Standards S5.1 and S5.3** offer alternate methods of presentation, Owner practice is to use the method requiring the fewest symbols.

Symbols will not be shown for the following:

- a) Valve positioners.
- b) Field mounted I/P transducers, when no solenoid valve or other device is in line between I/P and valve.
- c) Balloons identifying flow and temperature primary elements.
- d) Multiplexing, when used for panel mounted temperature indication only.
- e) Local process variable indicators on transmitter outputs, unless it is intended to designate a special location for the indicator, as shown by a note next to the tagging balloon.

2.0 FUNCTIONAL IDENTIFICATION

The functional identification of an instrument will consist of letters from **Table 1**, and will include on first-letter, covering the measured or initiating variable, and one or more succeeding letters covering the functions of the individual instrument. Exceptions to this rule are the use of the single letter L to denote a pilot light that is not part of an instrument loop and certain computer functions which will use modifying letters only.

The succeeding-letters of the functional identification designate one or more readout or passive functions, or output functions, or both. A modifying-letter may be used, if required, in addition to one or more other succeeding-letters. Modifying letters may modify either a first-letter or other succeeding-letters, as applicable. All letters of the functional identification shall be upper case. For examples of combinations of functional identification letters, see Table 2.

The functional designation associated with relays and computers may be used, as shown in **Table 3**, individually or in combination. The use of a box enclosing a symbol is required. The box is intended to avoid confusion by setting off the symbol from other markings on a diagram.



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TABLE 1 IDENTIFICATION LETTERS

	FIRST - L	ETTER (2.3.2)	SUCCEEDING - LETTERS				
	MEASURED OR INIATING VARIABLE	MODIFIER	READOUT OR PASSIVE FUNCTION	OUTPUT FUNCTION	MODIFIER		
Α	Analysis (2.3.4)		Alarm				
В	Burner, Combustion		User's Choice (2.3.1)	User's Choice (2.3.1)	User's Choice (2.3.1)		
С	Heating Value			Control	***************************************		
D	Density	Differential (2.3.2)	· ·				
E	Voltage		Sensor (Primary Element)				
F	Flow Rate	Ratio (Fraction) (2.3.2)					
G	User's Choice (2.3.1)		Glass, Viewing Device		A (A 44 A		
H	Hand				High		
l	Current (Electrical)		Indicate				
J	Power	Scan					
К	Time, Time Schedule	Time Rate of Change (2.3.2., 2.3.7)		Control Station (2.3.7)	***************************************		
L	Level		Light (2.3.5)		Low		
M	Energy	Momentary (2.3.2)			Middle Intermediate		
N	User's Choice (2.3.1)		User's Choice (2.3.1)	User's Choice (2.3.1)	User's Choice (2.3.1)		
0	User's Choice (2.3.1)	1	Orifice, Restriction				
P	Pressure, Vacuum		Point (Test)Connection				
Q	Quantity	Integrate, Totalize (2.3.2)					
R	Radiation		Record				
S	Speed, Frequency	Safety		Switch	117.710		
T	Temperature			Transmit			
U	Multivariable (2.3.8)		Multifunction (2.3.9)	Multifunction (2.3,9)	Multifunction (2.3.9)		
V	Vibration. Mechanical Analysis			Valve, Damper, Louver			
W	Weight, Force		Well				
Х	Unclassified (2.3.3)	X Axis	Unclassified (2.3.3)	Unclassified (2.3.3)	Unclassified (2.3.3)		
Y	Event, State or Presence	Y Axis		Relay, Compute Convert			
Z	Position, Dimension	Z Axis		Driver, Actuator, Unclassified Final Control Element			



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2.1 Notes For Table 1 - Meaning of Identification Letters

A user's choice letter is intended to cover unlisted meanings that will be used repetitively in a particular project. If used, the letter may have one meaning as a first-letter and another meaning as a succeeding-letter. For example, the letter N may be defined as "modulus of elasticity" as a first-letter and "oscilloscope" as a succeeding-letter.

Any first-letter, if used in combination with modifying letters D (differential or deviation), F (ratio), M (momentary), K (time rate of change), Q (integrate or totalize), or any combination of these is intended to represent a new and separate measured variable, and the combination is treated as a first-letter entity. Thus, instruments TDI and TI indicate two different variables, namely, differential- temperature and temperature. Modifying letters are used when applicable.

The unclassified letter X is intended to cover unlisted meanings that will be used only once or to a limited extent. If used, the letter may have any number of meanings as a first-letter and any number of meanings as a succeeding - letter. Except for its use with distinctive symbols, it is expected that the meanings will be defined outside a tagging balloon on a flow diagram. For example, XR-2 may be a stress recorder, XR-3 may be a vibration recorder, and XX-4 may be a stress oscilloscope.

First-letter A for analysis covers all analyses that are not listed in TABLE 1 and are not covered by a user's choice letter. It is expected that the type of analysis in each instance will be defined outside a tagging balloon on a flow diagram.

A pilot light that is part of an instrument loop should be designated by a first-letter followed by the succeeding- letter L. For example, a pilot light that indicates an expired time period should be tagged KQL. If it is desired to tag a pilot light that is not part of an instrument loop, the light is designated in the same way. For example, a running light for an electric motor may be tagged EL, assuming voltage to be appropriate measured variable, or YL, assuming the operating status is being monitored. The unclassified variable X should be used only for applications which are limited in extent. The designation XL should not be used for motor running lights, as these are commonly numerous. It is permissible to use the user's choice letters M, N or O for a motor running light when the meaning is previously defined. If M is used, it must be clear that the letter does not stand for the word "motor", but for a monitored state.

If a given loop has more than one instrument with the same functional identification, then a suffix shall be appended to the loop number, e.g. FV- 2A,FV-2B,etc., or TE-25-1, TE-25-2, etc.

However, if digital systems are involved, the use of suffixes may not be compatible and unique consecutive numbers shall be used. In such cases, using flow as an example, the main instrument should take the number of the Primary Case, e.g. with High and Low Flow arrangement, the transmitters shall be numbered, say FT-2 and FT-3, while the main instrument would be numbered FRC-2.

Modifying-letter K, in combination with a first-letter such as L, T, or W, signifies a time rate of change of the measured or initiating variable. The variable WKIC, for instance, may represent a rate-of-weight-loss controller.



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Succeeding-letter K is a user's option for designating a control station, while the succeeding-letter C is used for describing automatic or manual controllers.

Use of first-letter U for "multivariable" in lieu of a combination of first-letters is optional. It is recommended that nonspecific variable designators such as U be used sparingly.

Use of a succeeding-letter U for "multifunction" instead of a combination of other functional letters is optional.

This non-specific function designator should be used sparingly.



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TABLE 2 TYPICAL LETTER COMBINATIONS

		MEASURED VARIABLE RUMENT	ANALYSIS	DENSITY	FLOW	LEVEL	PRESSURE	PRESSURE DIFFERENTIAL	SPEED	TEMPERATURE	TEMPERATURE DIFFERENCE
ELEMENT INDICATOR TRANSMITTER RECORDER CONTROLLER INDICATING CONTROLLER RECORDING CONTROLLER CONTROL VALVE CONTROL VALVE CONTROL VALVE—SELF ACTING SWITCH—LOW SWITCH—HIGH ALARM—LOW ALARM—HIGH SOLENOID VALVE			AL AT	DE DE DEC DE SELECTION DE COMPANION DE COMPA	HELECTES - ELECTES	Entrope Cycles Aty	PE PI PR PC PC PC PSL PSH PAH PAH PY	PDE PDI PDT PDR PDC PDC PDCV PDCV PDSL PDSH PDAH PDAH PDY	SE SI ST SEC	HE THE CHECK TO THE TAIL THE T	DE DE CE DE
	# 8000000000000000000000000000000000000	BURNER FLAME DETECTOR FLAME DETECTION SWITCH ELECTRICAL CONDUCTIVITY PRO VOLTAGE INDICATOR INDICATION LIGHT FLOW SIGH GLASS (FLAPPER, FLOW RESTRICTION ORIFICE INDICATION OF INTEGRATED FL INDICATION WITH HAND CONTROL VALVE MANUAL LOADING STATION WITH HAND SWITCH WITH INDICATING MANUAL LOADING STATION WITH LEVEL GAUGE RUPTURE DISC RELIEF VALVE POSITION SWITCH (LOW OR CL POSITION SWITCH (HIGH OR O) LIGHT IND. LOW OR CLOSED F LIGHT IND. HIGH OR OPEN PO TREND RECORDER MULTIPLEXING UNIT, WHEN USI	ETC.) OW AND OW AND ARIZING) H OUTPU LIGHT H OUTPU OSED) PEN) OSEDON	IT GAUGI	E AND P	ROCESS	BNDICATI				



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TABLE 3 DESIGNATION FOR RELAYS AND COMPUTER FUNCTIONS

NO	FUNCTION	SYMBOL	DEFINITION
1	SUMMING	Σ	THE OUTPUT EQUALS THE ALGEBRAIC SUM OF THE INPUTS. (THE INPUTS MAY BE LABELED WITH POSITIVE OR NEGATIVE SIGNS).
2	AVERAGING	D/T	THE OUTPUT EQUALS THE ALGEBRAIC SUM OF THE INPUTS DIVIDED BY THE NUMBER OF INPUTS.
3	DIFFERENCE		THE OUTPUT EQUALS THE ALGEBRAIC DIFFERENCE OF THE TWO INPUTS.
4	PROPORTIONAL.	K 1:1 2:1	THE OUTPUT IS DIRECTLY PROPORTIONAL TO THE INPUT. IN THE CASE OF A VOLUME BOOSTER, "K" MAY BE REPLACED BY 1:1. FOR INTEGER GAINS, 2:1, 3:1,ETC., MAY BE SUBSTITUTED FOR K.
5	INTEGRAL	·	THE OUTPUT VARIES IN ACCORDANCE WITH BOTH MACHITUDE AND DURATION OF THE INPUT. THE OUTPUT IS PROPORTIONAL TO THE TIME INTEGRAL OF THE INPUT.
6	derivative	र्यस	THE OUTPUT IS PROPORTIONAL TO THE RATE OF CHANGE (DERIVATIVE) OF THE INPUT.
7	MULTIPLYING	×	THE OUTPUT EQUALS THE PRODUCT OF THE TWO INPUTS.
8	DIMIDING	÷	THE OUTPUT EQUALS THE QUOTIENT OF THE TWO INPUTS.
ð	ROOT EXTRACTION	~	THE OUTPUT EQUALS THE ROOT (I.E., CUBE ROOT, FOURTH ROOT, 3/2 ROOT, ETC.) OF THE INPUT. IF n IS OMITTED, A SQUARE ROOT IS ASSUMED.
10	exponential.	<u>x</u>	THE OUTPUT EQUALS THE INPUT RAISED TO A POWER (I.E., SECOND, THIRD, FOURTH, ETC.).
11	NONLINEAR OR UNSPECIFIED FUNCTION	f(x)	THE OUTPUT EQUALS SOME NONLINEAR OR UNSPECIFIED FUNCTION OF THE INPUT.
12	TIME FUNCTION	r(t)	THE OUTPUT EQUALS THE INPUT TIMES SOME FUNCTION OF TIME OR EQUALS SOME FUNCTION OF TIME ALONE.

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TABLE 3 (Contd.)

NO	FUNCTION	SYMBOL	DEFINITION						
13	HIGH SELECTING	2	THE OUTPUT IS EQUAL TO THE GREATER OF THE INPUTS.						
***	LOW SELECTING		THE OUTPUT IS EQUAL TO THE LESSER OF THE INPUTS.						
. [1]	HIGH LIMITING	*	THE OUTPUT EQUALS THE INPUT OR THE HIGH LIMIT VALUE WHICHEVER IS LOWER.						
16	LOW LEMITENC	*	THE OUTPUT EQUALS THE INPUT OR THE LOW LIMIT VALUE WHICHEVER IS HIGHER,						
17	REVERSE PROPORTIONAL	-*	THE OUTPUT IS REVERSELY PROPORTIONAL TO THE INPUT.						
18	VELOCITY LIMITER	. ¥	THE OUTPUT EQUALS THE INPUT AS LONG AS THE RATE OF CHANGE OF THE INPUT DOES NOT EXCEED A LIMIT VALUE. THE OUTPUT WILL CHANGE AT THE RATE ESTABLISHED BY THIS LIMIT UNTIL THE OUTPUT AGAIN EQUALS THE INPUT.						
19	BIAS	+ +	THE OUTPUT EQUALS THE INPUT PLUS (OR MINUS) SOME ARBITRARY VALUE (BIAS).						
20	CONVERT	*/*	THE FORM OF THE OUTPUT SIGNAL IS DIFFERENT FROM THAT OF THE INPUT. E-VOLTAGE A-ANALOG O-ELECTROMACNETIC, SONIC I-CURRENT B-BINARY R-RESISTANCE (ELECT.) P-PNEUMATIC H-HYDRAUUC D-DIGITAL						
		 							
21	SIGNAL MONITOR	**	THE OUTPUT HAS DISCRETE STATES WHICH ARE DEPENDENT ON THE VALUE OF THE INPUT, WHEN THE INPUT EXCEEDS (OR BECOMES LESS THAN) AN ARBITRARY LIMIT VALUE THE OUTPUT CHANGES STATE.						
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<u> </u>									



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3.0 LOOP IDENTIFICATION

The loop identification of an instrument will generally use a number assigned to the loop of which the instrument is a part. Each instrument loop shall have a unique number. An instrument common to two or more loops may have a separate loop number, if desired.

A consecutive numbering of instruments shall be used for each process variable of a contract. The loop numbering sequence for each process variable will begin with the number 001 and run consecutively until all loops in a given contract/process unit are identified.

It is Owner practice to assign a new contract number to each section of a multi-section job. Therefore, to discriminate between such sections, the functional identification letters will be followed by two digits of the process unit number, as follows:

FIC

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Functional

Unit

Progressive number

Identification

Number

4.0 **SYMBOLS**

It is not the intention of this standard to list all symbols or combinations. ISA Standards S5.1 and S5.3 list many more.

Control valve positioners and control valve electric-to-air converters will not be shown. Therefore, with an electrical system, the controller output (electrical) signal will be schematically shown connected to the valve diaphragm, while the actual installation will have a converter.

Various expedients may be used on individual contracts. For example, the letter "V" just outside the circle can indicate an item supplied by a Package Vendor.

The actuator action in the event of actuating medium failure shall be shown on control valves (see typical control valve symbols).

Software alarms shall follow ISA Standards sections 5.1 and 5.3. Letter designators shall be placed on the input or output signal lines of controls or other specific system function.

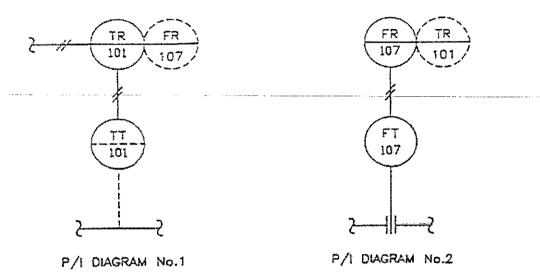


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When dual pen instruments are shown on different flow diagrams, a note can show "To second pen on TR-101" or the tangential circle can be shown in phantom as follows:



Computer functions will be shown as an hexagon. Use modifying letters only since the measured variable "UJ" is implied by the hexagon.

The symbols used to depict instrumentation on flow diagrams and other drawings are shown on **Appendix 1**.

5.0 ATTACHED DOCUMENTS

Appendix 1
 [Instrument Symbols]



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APPENDIX 1

CONNECTION TO PROCESS (Note	1)
UNDEFINED SIGNAL	
}	
PNEUMATIC SIGNAL (Note	2)
ELECTRIC SIGNAL	
HYDRAULIC SIGNAL	
CAPILLARY TUBING (FILLED SYSTEM)	
ELECTROMAGNETIC (NUCLEAR) OR SONIC SIGNAL (Note (GUIDED)	3)
C C ELECTROMAGNETIC OR SONIC SIGNAL (Note (NOT GUIDED)	3)
MECHANICAL LINK	
OPTIONAL BINARY (ON-OFF) SYMBOLS	
PNEUMATIC BINARY SIGNAL	
Notes:	
1. All lines to be fine in relation to process piping lines. 2. The pneumatic signal symbol applies to a signal using any gas as the signal medium. If a gas other than die to used the control of the signal medium.	
If a gas other than air is used, the gas may be identified by a note on the signal symbol or otherwise. 3. Electromagnetic phenomena include heat, radio waves, nuclear radiation, and light.	SA-PARAMETERS

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GENERAL INSTRUMENT OR FUNCTION SYMBOLS

	PRIMARY LOCATION *** NORMALLY ACCESSIBLE TO OPERATOR	FIELD MOUNTED	AUXILIARY LOCATION *** NORMALLY ACCESSIBLE TO OPERATOR
DISCRETE INSTRUMENTS	iP1**		-3
SHARED DISPLAY, SHARED CONTROL	→	5	6
COMPUTER FUNCTION	7	8	9
PROCRAMMABLE LOGIC CONTROL	10	11	12

circle size for	large diagrams	g to the a shown	user's above.	needs and the Consistency is	type of	f document . nended.	A	suggested s	Grate	ซกต
-----------------	----------------	---------------------	------------------	---------------------------------	---------	-------------------------	---	-------------	-------	-----

***	Normally	inoccessible	or behind	i-the-pane	devices	or functi	ons may	be	depicted	by us	sing the	same	symbol:
	but with	dashed horiz	zontal ber	s. i.e. (\bigcirc		$\langle - \rangle$,					Î

Abbreviations of the user's choice such as IP1 (instrument Panel #1), IC2 (instrument Console #2), CC3 (Computer Console #3) etc., may be used when it is necessary to specify instrument or function location.



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GENERAL INSTRUMENT OR FUNCTION SYMBOLS (Contd.)

13	14	15		
	TE 31001.23			
REPORT ON PRINTER	instrument with Long tag number	INSTRUMENTS SHARING COMMON HOUSING		
16	17 C 12	18 \(\hat{p}\)		
PILOT LIGHT	PANEL MOUNTED PATCHBOARD POINT 12	PURGE OR FLUSHING DEVICE		
19	20 .	21		
⟨R⟩	₩	\Diamond		
RESET FOR LATCH—TYPE ACTUATOR	DIAPHRAGM SEAL	UNDEFIND INTERLOCK LOGIC		

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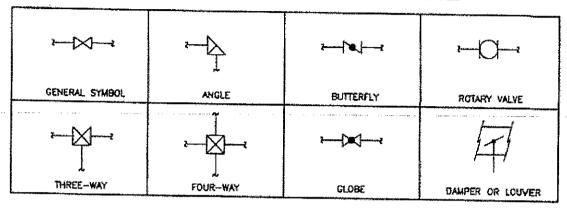
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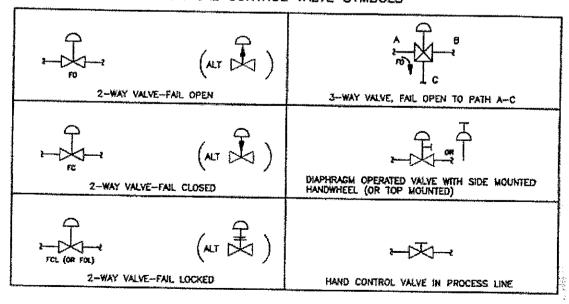
CONTROL VALVE BODY SYMBOLS, DAMPER SYMBOLS



ACTUATOR SYMBOLS

			Management and the second seco
7	F	(8)	S
DIAPHRAGII TYPE ACTUATOR	PISTON TYPE ACTUATOR	MOTOR ACTUATOR	SOLENDID ACTUATOR

TYPICAL CONTROL VALVE SYMBOLS





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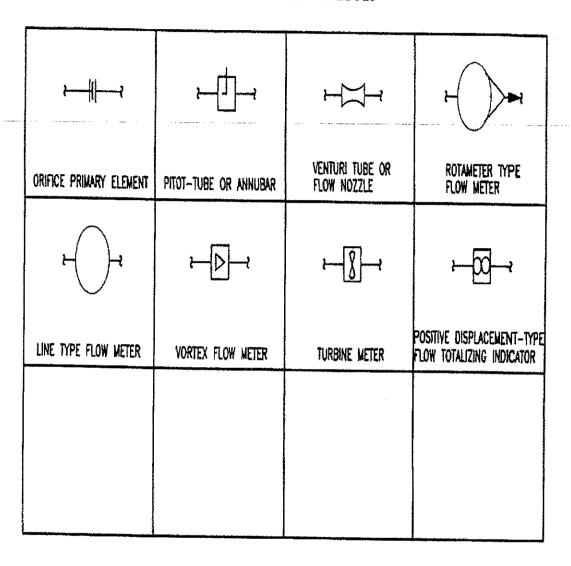
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PRIMARY ELEMENT SYMBOLS



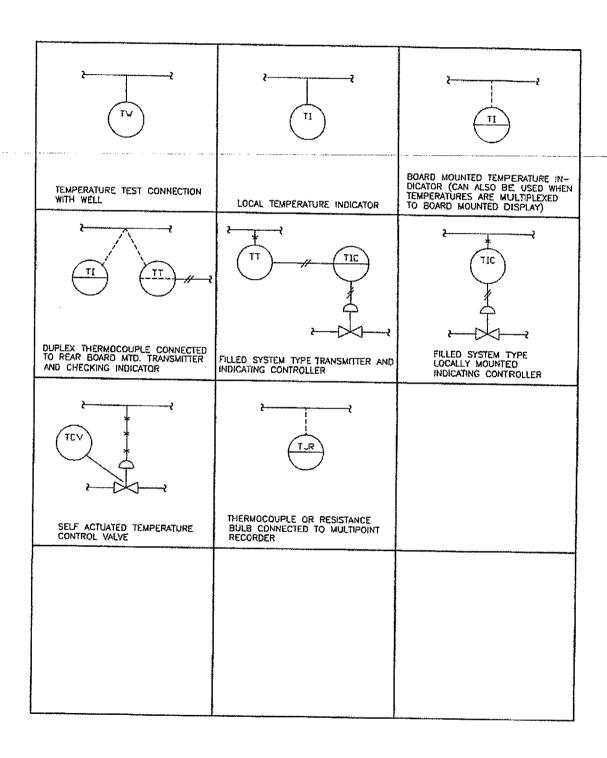


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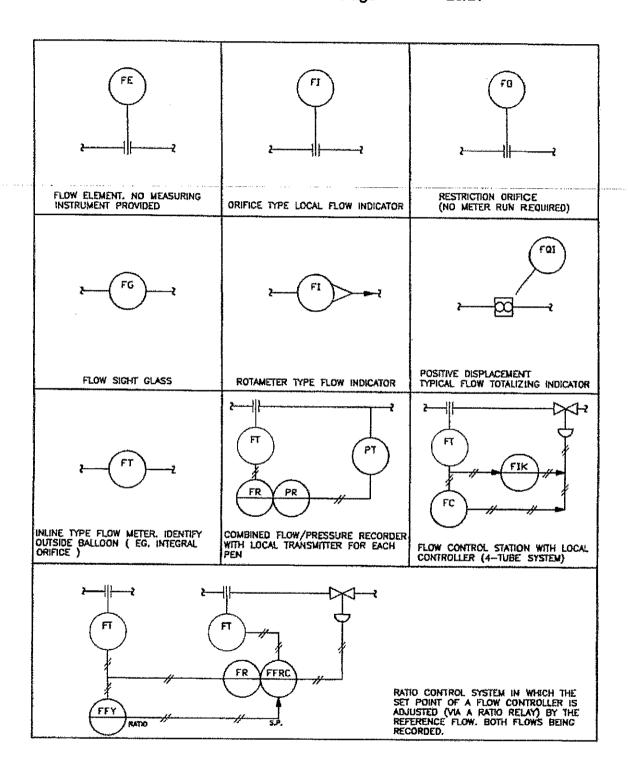






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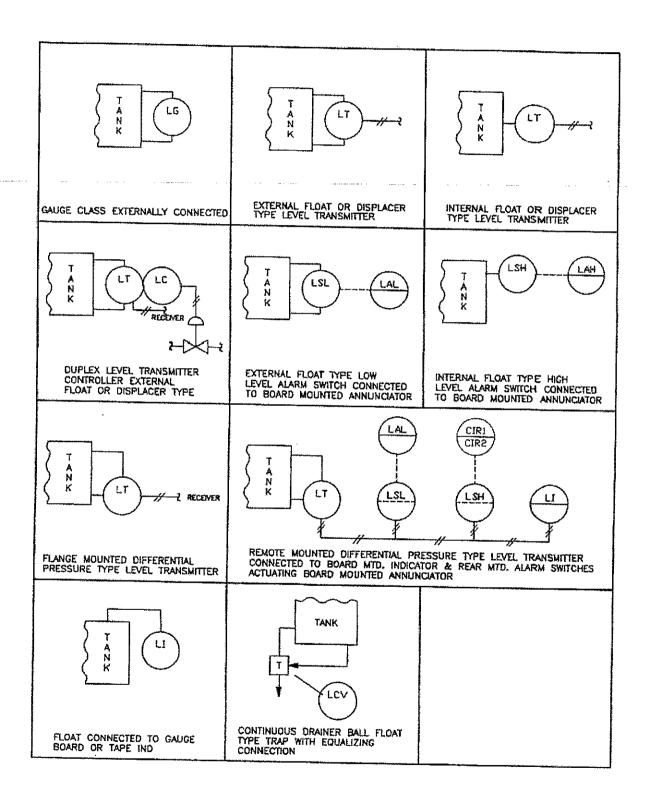


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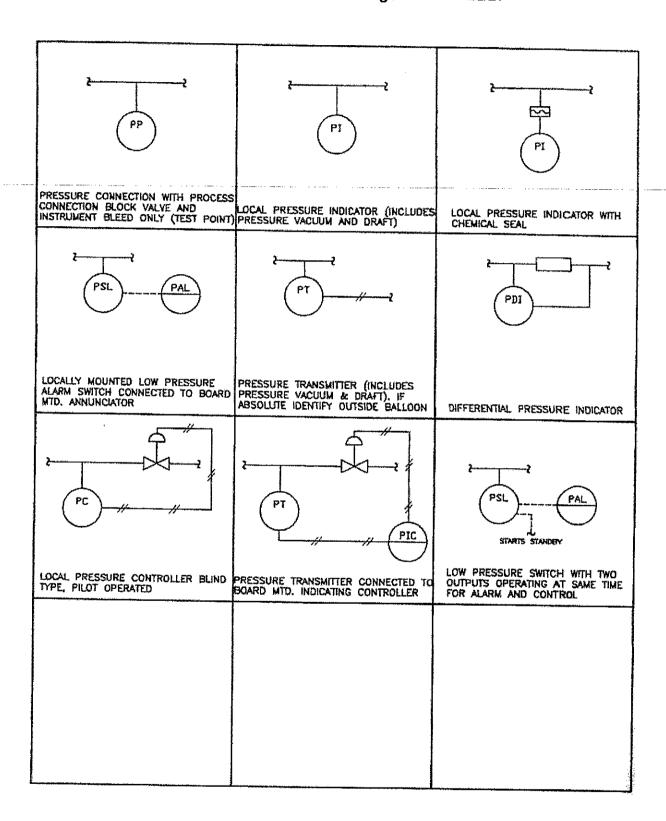


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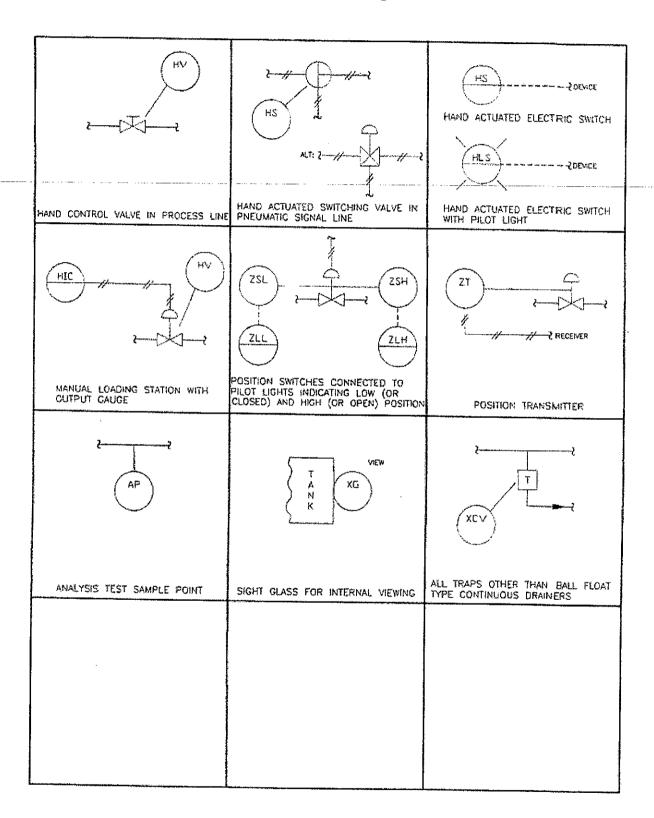


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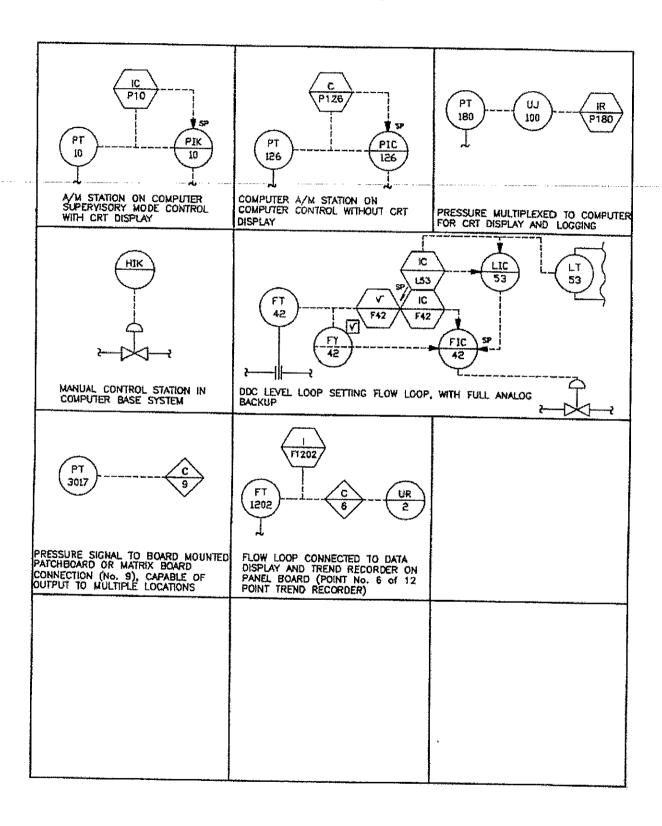


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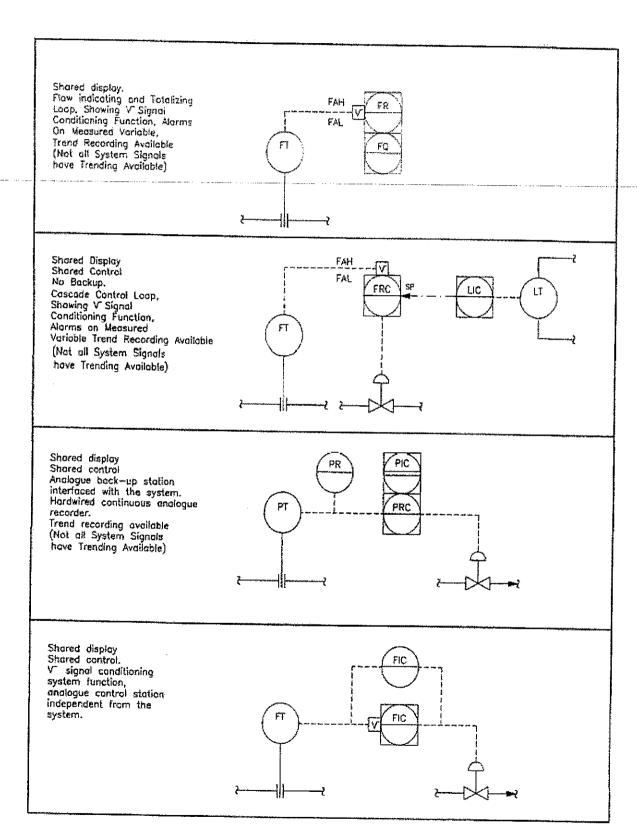




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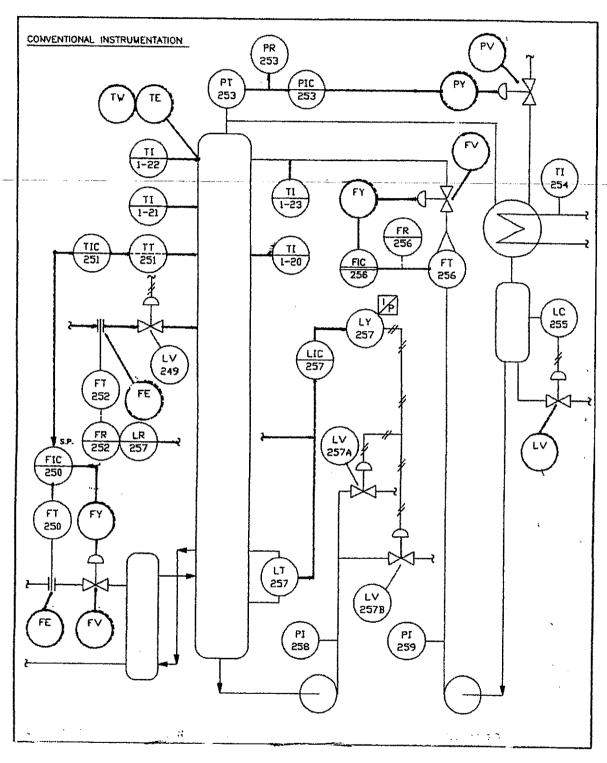


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